### The Kernel Matrix Diffie-Hellman Assumption

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#### **Outline**

Introduction

- Introduction
- The Kernel Matrix Diffie-Hellman Assumption
- Hardness of the KerDH Assumption
- The Case  $\ell > k+1$

### Additive (Implicit) Notation

Introduction

Given a group  $\mathcal{G}$  of prime order q and a generator  $g \in \mathcal{G}$ :

$$\begin{array}{cccc}
g^{x} & \rightarrow & [x] \\
g & \rightarrow & [1] \\
1 & \rightarrow & [0] \\
g^{x}g^{y} & \rightarrow & [x][y] = [x+y] \\
(g^{x})^{y} & \rightarrow & [x]^{y} = [xy] \\
(g^{x_{1}}, \dots, g^{x_{n}}) & \rightarrow & [x_{1}, \dots, x_{n}] \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
g^{x_{n1}} \cdots g^{x_{nm}} & \rightarrow & \begin{bmatrix} x_{11} \cdots x_{1m} \\ \vdots & \vdots \\ x_{n1} \cdots x_{nm} \end{bmatrix}
\end{array}$$

Given a (symmetric) bilinear map  $e: \mathcal{G} \times \mathcal{G} \to \mathcal{G}_T$ :

$$e(g^x, g^y) = g_T^{xy} \rightarrow e([x], [y]) = [xy]_T$$



Introduction

# Subspace Membership Problems

For a  $(k, \ell)$ -collection of vector subspaces of dimension k,  $S = \{S_i\}_{i \in \mathcal{I}}$ , of the vector space  $\mathbb{Z}_q^{\ell}$ , where  $0 < k < \ell$ 

#### Definition (Subspace Membership Problem)

Given  $\mathcal{G}$  and g, tell apart

$$D_{\text{real}} = ([S], [\mathbf{z}])$$
 for random  $S \leftarrow S$  and  $\mathbf{z} \leftarrow S$ 

$$D_{\mathsf{random}} = ([S], [\mathbf{z}]) \text{ for random } S \leftarrow \mathcal{S} \text{ and } \mathbf{z} \leftarrow \mathbb{Z}_q^{\ell}$$

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Typically,  $S = \operatorname{Span} A$ , where  $A \in \mathbb{Z}_{\sigma}^{\ell \times k}$  and  $\operatorname{rank} A = k$ .



# Subspace Membership Problems

DDH: 
$$A(\mathbf{a}) = \begin{pmatrix} 1 \\ \mathbf{a} \end{pmatrix}$$
  $\mathbf{a} \leftarrow \mathbb{Z}_q$ 

$$\mathbf{z} = \begin{pmatrix} 1 \\ \mathbf{a} \end{pmatrix} (\mathbf{w}) = \begin{pmatrix} \mathbf{w} \\ \mathbf{a} \mathbf{w} \end{pmatrix} \text{ vs. } \mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$

2-Lin: 
$$A(a_1, a_2) = \begin{pmatrix} a_1 & 0 \\ 0 & a_2 \\ 1 & 1 \end{pmatrix}$$
  $a_1, a_2 \leftarrow \mathbb{Z}_q$ 

$$\mathbf{z} = \begin{pmatrix} a_1 & 0 \\ 0 & a_2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} a_1 w_1 \\ a_2 w_2 \\ w_1 + w_2 \end{pmatrix} \text{ vs. } \mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix}$$

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"Matrix distributions"
$$\mathbf{z} = \begin{pmatrix} a_1 & 0 \\ 0 & a_2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} a_1 & w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} a_1 & w_1 \\ a_2 & w_2 \\ w_1 + w_2 \end{pmatrix} \text{ vs. } \mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix}$$

#### Matrix Distributions

Given  $1 \le k < \ell$ ,

#### Definition (Polynomial Matrix Distribution)

 $A \leftarrow \mathcal{D}_{\ell,k}^f$ , where  $A \in \mathbb{Z}_q^{\ell \times k}$ , rank A = k and A is sampled according to  $A = f(a_1, \ldots, a_d)$ , where  $a_1, \ldots, a_d \leftarrow \mathbb{Z}_q$  and f is a polynomial map of constant degree.

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E.g. 
$$A(a) = \begin{pmatrix} 1 \\ a \end{pmatrix}$$
  $A(a_1, a_2) = \begin{pmatrix} a_1 & 0 \\ 0 & a_2 \\ 1 & 1 \end{pmatrix}$ 

Introduction

# Matrix Decision Diffie-Hellman (MDDH) Problems

### Definition ( $\mathcal{D}_{\ell,k}^{A}$ -MDDH Problem [EHKRV13])

Tell apart the two probability distributions

$$D_{\text{real}} = (\mathcal{G}, q, g, [A(t)], [A(t)w]), t \leftarrow \mathbb{Z}_q^d, w \leftarrow \mathbb{Z}_q^k$$

$$D_{\mathsf{random}} = (\mathcal{G}, q, g, [A(t)], [z]), \ t \leftarrow \mathbb{Z}_q^d, \ z \leftarrow \mathbb{Z}_q^\ell$$

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Generic hardness depends on the degree and irreducibility of the determinant polynomial  $\mathfrak{d}(t,z) = \det(A(t)||z)$ 

#### **Known Instances**

Introduction 0000000

$$A_{k\text{-Unif}} = \begin{pmatrix} t_{1,1} & \cdots & t_{1,k} \\ \vdots & \ddots & \vdots \\ t_{k+1,1} & \cdots & t_{k+1,k} \end{pmatrix}$$

$$A_{k ext{-Unif}} = egin{pmatrix} t_{1,1} & \cdots & t_{1,k} \ dots & \ddots & dots \ t_{k+1,1} & \cdots & t_{k+1,k} \end{pmatrix} \qquad A_{k ext{-Lin}} = egin{pmatrix} t_1 & 0 & \cdots & 0 \ 0 & t_2 & \ddots & dots \ dots & \ddots & \ddots & 0 \ 0 & \cdots & 0 & t_k \ 1 & 1 & \cdots & 1 \end{pmatrix}$$

$$A_{k\text{-Casc}} = \begin{pmatrix} t_1 & 0 & \cdots & 0 \\ 1 & t_2 & \ddots & \vdots \\ 0 & \ddots & \ddots & 0 \\ \vdots & \ddots & 1 & t_k \\ 0 & \cdots & 0 & 1 \end{pmatrix} \qquad A_{k\text{-SCasc}} = \begin{pmatrix} t & 0 & \cdots & 0 \\ 1 & t & \ddots & \vdots \\ 0 & \ddots & \ddots & 0 \\ \vdots & \ddots & 1 & t \\ 0 & \cdots & 0 & 1 \end{pmatrix}$$

$$A_{k\text{-SCasc}} = \begin{pmatrix} t & 0 & \cdots & 0 \\ 1 & t & \ddots & \vdots \\ 0 & \ddots & \ddots & 0 \\ \vdots & \ddots & 1 & t \\ 0 & \cdots & 0 & 1 \end{pmatrix}$$

# **Applications**

#### Some known applications:

- Public key encryption
- Hash Proof systems
- Pseudorandom functions
- Non-interactive Zero-Knowledge proofs (Groth-Sahai)
- Efficient Proofs for CRS-Dependent Languages

**Key idea:** Most constructions based on DDH or 2-Lin are actually valid for any MDDH problem

#### We can obtain

- more compact instances
- more secure instances (secure even when an efficient multilinear map is available)

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# Flexible Computational Matrix Problems

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(Flexible) computational problems: Capture forgery adversarial capabilities. E.g. breaking

- unforgeability of a digital signature
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- binding property of a commitment
- ...

We unify some existing flexible computational problems in the literature in a single framework.



## The Kernel Matrix Diffie-Hellman Assumption

For a  $(r, \ell)$ -collection of vector subspaces of dimension r,  $S = \{S_i\}_{i \in \mathcal{I}}$ , of the vector space  $\mathbb{Z}_q^{\ell}$ , where  $0 < r < \ell$ 

#### Definition (Subspace Sampling Problem)

Given  $\mathcal{G}$ , g and [S], find [x] where x is a nonzero vector in S

Typically  $S = \ker A^{\top}$ , where  $A \in \mathbb{Z}_q^{\ell \times k}$ , rank A = k and  $r = \ell - k$ .



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## Definition ( $\mathcal{D}_{\ell_k}^A$ -KerMDH Problem)

Given [A], where  $A \leftarrow \mathcal{D}_{\ell,k}$  find a nonzero vector [x] such that  $\mathbf{x}^{\mathsf{T}} A = \mathbf{0}.$ 

The  $\mathcal{D}_{\ell k}^{A}$ -KerDH Assumption states that the above problem is hard, w.r.t. and instance generator  $(q, \mathcal{G}, q) \leftarrow \mathcal{I}$ 



# KerMDH Examples

**DDH Kernel:** 
$$A(a) = \begin{pmatrix} 1 \\ a \end{pmatrix}$$
  $a \leftarrow \mathbb{Z}_q$ 

Given [A], find  $[x_1, x_2] \neq [\mathbf{0}]$  such that

$$\begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} 1 \\ a \end{pmatrix} = x_1 + ax_2 = 0$$

**2-Lin Kernel:** 
$$A(a_1, a_2) = \begin{pmatrix} a_1 & 0 \\ 0 & a_2 \\ 1 & 1 \end{pmatrix} \quad a_1, a_2 \leftarrow \mathbb{Z}_q$$

Given [A], find  $[x_1, x_2, x_3] \neq [\mathbf{0}]$  such that

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#### Just Take

$$[x_1, x_2] = [-a, 1]!$$

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 $[x_1, x_2, x_3] = [-a_2\lambda, -a_1\lambda, a_1a_2\lambda]$  for some  $\lambda$ . Hard to compute from  $[a_1]$ ,  $[a_2]$ !

### More Examples

#### Lemma (KerMDH vs. MDDH)

In pairing groups,  $\mathcal{D}_{\ell,k}^{A}$ -MDDH  $\Rightarrow \mathcal{D}_{\ell,k}^{A}$ -KerDH

 $D_{\text{real}}$ :

$$\mathbf{x}^{\mathsf{T}} A \mathbf{w} = 0 \quad \Rightarrow \quad \mathbf{x}^{\mathsf{T}} (A \mathbf{w}) = 0 \quad \Rightarrow \quad e([\mathbf{x}^{\mathsf{T}}], [A \mathbf{w}]) = [0]_{\mathsf{T}}$$

 $D_{\text{random}}$ :

$$\mathbf{z} \leftarrow \mathbb{Z}_q^\ell \quad \Rightarrow \quad \mathbf{x}^{\top} \mathbf{z} \neq \mathbf{0} \quad \Rightarrow \quad e([\mathbf{x}^{\top}], [A\mathbf{w}]) \neq [\mathbf{0}]_{\mathcal{T}} \quad \text{w.o.p.}$$

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 $D_{\rm random}$ :

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All hard MDDH instances define hard KerMDH instances: *k*-Unif, *k*-Lin, *k*-Casc, *k*-SCasc, . . .



## The KerMDH Family

- KerMDH integrates some previously known assumptions:
  - Find-Rep [Brands93]
  - Simultaneous Double Pairing [AFGHO10]
  - Triple Pairing [Groth10]
  - Simultaneous Pairing [GL07]
  - 1-Flexible Diffie-Hellman [LV08]
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- Applications:
  - Homomorphic Signatures [LPJY13]
  - Quasi-Adaptive NIZK [KW15]
  - Trapdoor Commitments to Group Elements
  - Structure Preserving Signatures [KPW15], ...



### The power of KerMDH

Designated-verifier proof of membership:

Given [x] and [M], prove that x = Mw for some w.

**Designated verifier keys:** Secret K, public  $[M^TK]$ .

**Proof:**  $[\pi]$  such that  $\pi^{\top} = \mathbf{x}^{\top} K$ .

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Using  $\mathcal{D}_{\ell,k}$ -KerDH, Publicly verifiable proof:

**Public parameters:**  $[M], [M^TK], [A], [KA], A \leftarrow \mathcal{D}_{\ell,k}$ .

**Proof:**  $[\pi]$  such that  $e([\pi^\top], [A]) = e([\mathbf{x}^\top], [KA])$ .

$$\boldsymbol{\pi}^{\top} A = \boldsymbol{x}^{\top} K A \quad \Leftrightarrow \quad (\boldsymbol{\pi}^{\top} - \boldsymbol{x}^{\top} K) A = \boldsymbol{0} \quad \Rightarrow \quad \boldsymbol{\pi}^{\top} = \boldsymbol{x}^{\top} K$$

or  $\mathcal{D}_{\ell,k}$ -KerDH is easy.



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- **Increasing Hardness:** For the typical families of hard  $\mathcal{D}_{\ell,k}$  of increasing size  $\mathcal{D}_{k+1}^{A}$ -KerDH  $\Rightarrow \mathcal{D}_{k}^{A}$ -KerDH

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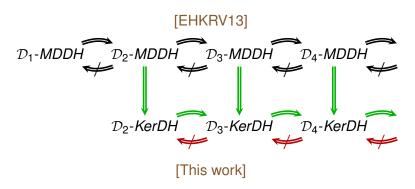
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**Explicit Reductions** 

**Black-Box Separation** 



### Families with Increasing Hardness



Valid for all families: k-Unif, k-Lin, k-Casc, k-SCasc.



 $\mathcal{P}_1 \stackrel{\mathsf{BB}}{\Rightarrow} \mathcal{P}_2$  means that a reduction  $\mathcal{R}$  solves  $\mathcal{P}_1$  using **any** possible oracle solving  $\mathcal{P}_2$ .



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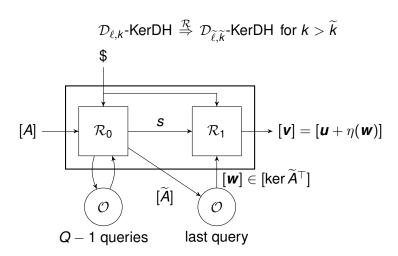
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We impose some extra requirements to  $\mathcal{R}$ :

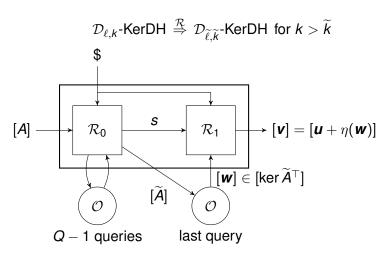
- It is generic (it works on the generic k-linear group model),
- It makes a constant number of calls Q to the  $\mathcal{P}_2$  oracle.



### BB Separation: Reduction Splitting



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- Generic model:  $\eta$  is linear and it only depends on \$.
- dim  $Im(\eta) < k$



# **BB Separation: Query Supression**

### Definition (*k*-Elusiveness)

A  $(r, \ell)$ -collection of vector subspaces S is k-elusive if given any k-vector subspace F,

$$\Pr[S \cap F \neq \{\mathbf{0}\} : S \leftarrow S] \in \mathbf{negl}$$

### **BB** Separation: Query Supression

### Definition (k-Elusiveness)

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#### Lemma

For any hard matrix distribution  $\mathcal{D}_{\ell,k}$ , the collection of subspaces  $\{\ker A^{\top}\}_{A\in\mathcal{D}_{\ell,k}}$  is k-elusive.



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We prove the last oracle call does not help the reduction.

By induction, if  $\mathcal{R}$  exists then  $\mathcal{D}_{\ell,k}$ -KerDH can be solved directly (e.g. Q = 0).

### Larger Kernel Problems are strictly harder!

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# A New Matrix Distribution With $\ell > k + 1$

(k, d)-Circ: A compact hard matrix distribution with  $\ell > k+1$ 

$$A_{(k, d) ext{-Circ}} = egin{pmatrix} t_1 & & & & 0 \ dots & t_1 & & & \ t_d & dots & \ddots & & \ 1 & t_d & & & t_1 \ & 1 & \ddots & dots \ & & \ddots & dots \ 0 & & & 1 \end{pmatrix}$$

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- Optimal representation size for hard  $(k + d) \times k$  polynomial matrix distributions of degree 1
- Application: Compact public key structure preserving commitments to vectors (see paper)



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We prove that the set of (k + 1)-minors of (A(t)|z) for (k, d)-Circ is a Gröbner basis of  $\mathfrak{I}$ , and all minors have total degree k + 1. Then, no nonzero polynomial of degree  $\leq k$  exist in J.



# Optimal Compactness of (k, d)-Circ

#### **Theorem**

Any hard polynomial matrix distribution  $\mathcal{D}_{\ell,k}^{A}$  of degree 1, has at least  $\ell-k$  parameters.



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Any hard polynomial matrix distribution  $\mathcal{D}_{\ell,k}^{A}$  of degree 1, has at least  $\ell-k$  parameters.

If  $d < \ell - k$ : apply gaussian row elimination with scalar coefficients to the matrix  $A(t) \leftarrow \mathcal{D}_{\ell,k}^f$  to put at least  $\ell - (d+1) \geq k$  zeros in the first column.

There exists an invertible matrix  $L \in GL_{\ell}(\mathbb{Z}_q)$  such that LA(t) has an identically zero k-minor.

LA(t) defines an easy MDDH problem. Therefore,  $\mathcal{D}_{\ell,k}$ -MDDH is also easy.



### The Kernel Matrix Diffie-Hellman Assumption

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Matemática Aplicada a la Criptografía

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The End!

